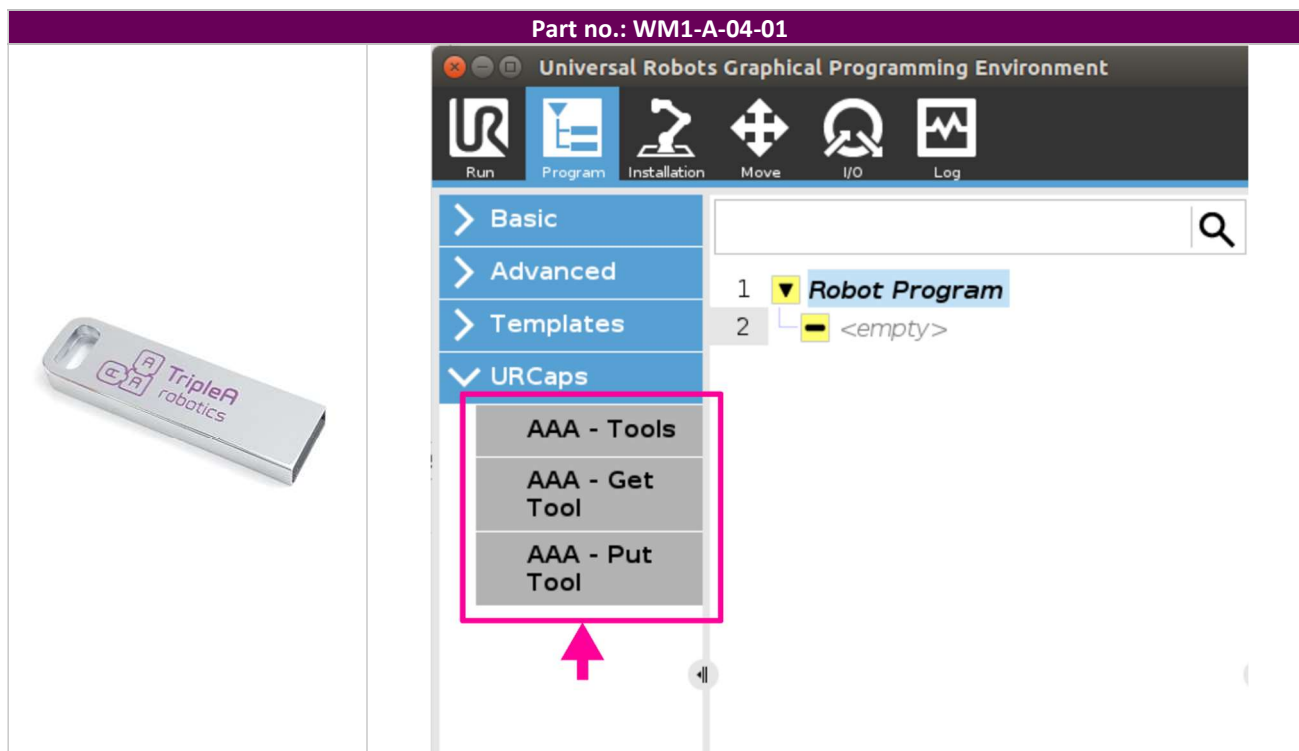


Datasheet – URcap software



PART NUMBERS

Pos.:	Part no.:	Description:	Interfaces with:
	WM1-A-04-01	UR cap software. License for use on one robot.	Universal robots

TECHNICAL DATA

For use on:	Universal Robots: CB3 series installed with Polyscope version 3.13 or later and e-series installed with Polyscope version 5.8 or later.
License:	License for use on one robot only.
Main features:	AAA – Tools > Add this node in top of your robot program and configure your end-effectors here. AAA – Get Tools > Add this node to you robot program when you want the robot to get an end-effector. AAA – Put Tool > Add this node to you robot program when you want the robot to put back an end-effector. <ol style="list-style-type: none"> 1. 1-minute tool change setup as only one waypoint must be teached per end-effector. 2. Store data in the robot program for all your favorite end-effectors. 3. Easy toggle of e.g. payload, TCP, COG and tool voltage in tool changes. 4. Optional exit and enter waypoints to ensure free passage to and from the tool area. 5. Adjustment of the tool changers orientation on the robot to allow odd orientation e.g. for use in double mount applications. 6. Several possibilities to optimize tool change waypoints. 7. Optimized to ensure no conflicts with other URcaps installed on the robot (e.g. no threads running in the background and no interference with Tool IO's).